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**Buliding blocks** 

- Rain-gauge observations:  $\mathbf{y}^{\mathrm{o}}$
- Background field  $\leftarrow$  radar estimates:  $\mathbf{x}^{b}$  on gridpoints,  $\mathbf{y}^{b}$  on station points
- Innovation:  $\mathbf{y}^o \mathbf{y}^b$

valid observations 12h 06DEC2015

valid observations 12h 27JUN2014



Preliminary choice

- Use the same interpolation parameters in convective and stratiform precipitation events
- Compromise
- Questionable...
- Otherwise 1: change parameters with season or month?
- Otherwise 2: Detect proportion convective /stratiform: how?
  - Use model forecasts?
  - Analysis of radar estimation "fields"?
- Not for the moment







 $dy = y^o - y^b \pmod{m}$ 

Choices:

 Separate areas (gridpoints and station points) where precipitation is occurring from areas where there is no precipitation



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- Separate areas (gridpoints and station points) where precipitation is occurring from areas where there is no precipitation
- Where it rains, assume that it rains at least as much as the radar estimates: x<sup>b</sup> on gridpoints, y<sup>b</sup> on station points
  - Make use of rain-gauge measurements y<sup>o</sup> only where they are larger than the corresponding radar estimate y<sup>b</sup>
  - Then innovation is positive:  $\mathbf{y}^{o} \mathbf{y}^{b} > 0$
  - A rain-gauge observation is considered *innovative* only when it exceeds the radar estimate used as background value.



2014-06-27 : (yo-yb) [yb>X0 AND yo>yb]

5514

765



2015-12-06 : (yo-yb) [yb>X0 & yo>=yb]



Less than 10 mm: 762

Choices:

- Separate areas (gridpoints and station points) where precipitation is occurring from areas where there is no precipitation
- Where it rains, assume that it rains at least as much as the radar estimates: x<sup>b</sup> on gridpoints, y<sup>b</sup> on station points
  - Make use of rain-gauge measurements y<sup>o</sup> only where they are larger than the corresponding radar estimate y<sup>b</sup>
  - Then innovation is positive:  $\mathbf{y}^o \mathbf{y}^b > 0$
  - A rain-gauge observation is considered *innovative* only when it exceeds the radar estimate used as background value.
- Then, proceed with usual O. I. (Optimal interpolation)
  - Questionable: still non-gaussian (skewed: gamma?)
  - Small ratio  $\sigma_0^2/\sigma_b^2 = 0.1$ : give confidence to these observations.

Precipitation analysis combining rain-gauge observations with radar estimates **OI and covariances** 



**G**: (I,M) : background error covariance gridpoints – observation points **S**: (M,M): background error covariance observation points – observation points **R**: (M,M): observation error covariance (assumed diagonal) Precipitation analysis combining rain-gauge observations with radar estimates Background Correlation function(s)

- $d_{im}$ : distance between (grid/station) point *i* and station point *m*
- c : radar attenuation class at (grid/station) point *i*
- $D_{h}$ : decorrelation distance

$$G_{i,m} \text{ or } S_{i,m} = \sigma_b^2 \left( 1 + \frac{d_{i,m}}{D_h} \right) \exp\left(-\frac{d_{i,m}}{D_h}\right) \cdot \left[ 1 - (c_i - c_m)^2 \right]$$
$$G_{i,m} \text{ or } S_{i,m} = \sigma_b^2 \exp\left[-\frac{1}{2} \left(\frac{d_{i,m}}{D_h}\right)^2\right]$$

**G**: (*I*,*M*) : background error covariance gridpoints – observation points **S**: (*M*,*M*): background error covariance observation points – observation points **R**: (*M*,*M*): observation error covariance (assumed diagonal)  $\mathbf{R} = \sigma_o^2 \mathbf{I}$ 

 $D_h$ : tested various values, best results for  $D_h$  = 20 km;  $\sigma_o^2/\sigma_b^2 = 0.1$  Precipitation analysis combining rain-gauge observations with radar estimates Separate areas: precipitation / no precipitation

Choices:

- Threshold  $X_0 = 0.02 \text{ mm}$
- "ZERO" obs:  $0 < y^{\circ} < X_{0} \rightarrow IDI$  (Integral Data Influence, grid and station points):  $IDI_{7}$
- "POSITIVE" obs:  $y^o > X_o \& y^o > y^b$  larger than  $X_o AND$  than background  $\rightarrow IDI_p$
- IDI = Integral Data Influence:

analysis of all "observations" = 1, with background = 0

IDI= 0 far from obs, IDI~1 in densely observed areas.

$$\mathbf{IDI} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \mathbf{G} (\mathbf{S} + \mathbf{R})^{-1} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

• Compare  $IDI_z$  and  $IDI_P$  with a threshold value:  $IDI_{MIN} = 0.2$ 

 $IDI_{z,P} < IDI_{MIN}$  then  $IDI_{z,P} = Z$  (zero), otherwise  $IDI_{z,P} = P$  (positive)

Precipitation analysis combining rain-gauge observations with radar estimates Separate areas: precipitation / no precipitation

Xp	IDIZ	IDIP	X <sup>a</sup>	Do:
U	Z	Z	U	x <sup>a</sup> ← UNDEF
U	Z	Ρ	Ρ	x <sup>b</sup> ← 0, then compute analysis
U	Р	Z	Z	X <sup>a</sup> ← <b>0</b>
U	Р	Ρ	Ρ	IDIP prevails: $\mathbf{x}^{b} \leftarrow 0$ , then <b>compute analysis</b>
Ζ	Z	Z	Z	<b>X</b> <sup>a</sup> ← <b>0</b>
Z	Z	Р	Ρ	compute analysis
Ζ	Р	Z	Z	X <sup>a</sup> ← <b>0</b>
Z	Р	Ρ	Ρ	IDIP prevails: compute analysis
Р	Z	Z	Ρ	$\mathbf{X}^{\mathbf{a}} \leftarrow \mathbf{X}^{\mathbf{b}}$
Р	Z	Ρ	Ρ	compute analysis
Р	Р	Z	Р	$\mathbf{X}^{\mathbf{a}} \leftarrow \mathbf{X}^{\mathbf{b}}$
Ρ	Р	Ρ	Ρ	IDIP prevails: compute analysis

 $IDI_{z,P} < IDI_{MIN} \Rightarrow IDI_{z,P} = Z$  (zero); otherwise  $IDI_{z,P} = P$  (positive); U = UNDEFined value

## Separate areas: precipitation / no precipitation

valid observations 12h 06DEC2015



valid observations 12h 27JUN2014



## Separate areas: precipitation / no precipitation

green:IDIZ blue:IDIP 12h 06DEC2015





green:IDIZ blue:IDIP 12h 27JUN2014

**RADAR ESTIMATE = Background and rain-gauge observations** 



2 3 5 7 10 15 20 30 5<mark>0 70 100</mark>





#### 2 3 5 7 10 15 20 30 50 70 100



## xa and yo 12h 27JUN2014



and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 

Analysis: RADAR + RAINGAUGES



Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Background RADAR estimate

Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Background RADAR estimate

Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Background RADAR estimate

Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 



Background RADAR estimate

Analysis increment  $\mathbf{x}^{a}$ - $\mathbf{x}^{b}$ and innovation  $\mathbf{y}^{o}$ - $\mathbf{y}^{b}$ 

## **CV-score and RMS of innovation**

The CV-score is the RMS residual from the CV-analysis, obtained at each obs location by not using its observed value, but using all other observations. Compared with RMS residual raingauge-radar.



## WINTER CASE

Stratiform precipitation is rather smoothly distributed in space: the CV-score is a meaningful measure of analysis error.

### SUMMER CASE

Convective precipitation may happen to be detected by just one rain-gauge: the CV-score may fail as a measure of analysis error.

## Conclusions

- Precipitation analysis combining rain-gauge observations and radar estimates
- Operational choices:
  - Separation RAIN/NO RAIN areas
  - Use a raingauge observation only if it exceeds the corresponding radar estimate ("innovative" observation)
  - Optimal Interpolation radar  $\rightarrow$  background, raingauges  $\rightarrow$  observations
- Separation RAIN /NO RAIN areas by means of IDI (Integral Data Influence) fields of:
  - "ZERO" observations less than threshold 0.02 mm
  - "POSITIVE" observation larger than threshold and radar
- Correlation function depending on distance and radar attenuation class
- Raingauge observations compensate for radar attenuation in stratiform cases
- Radar estimation (better than raingauges in convective cases) not degraded by raingauges interpolation
- DEVELOPMENTS: gamma distribution? Include model fields? Change parameters with season? Separate stratiform and convective precipitation?